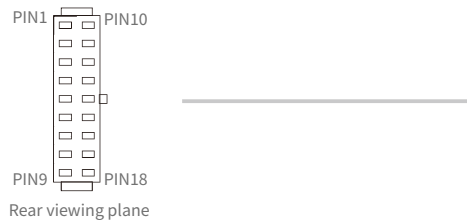


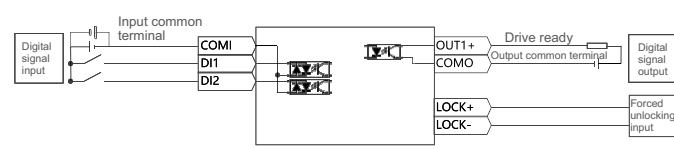
Terminal definition

iWMC Integrated Servo Wheel Control Wiring Diagram

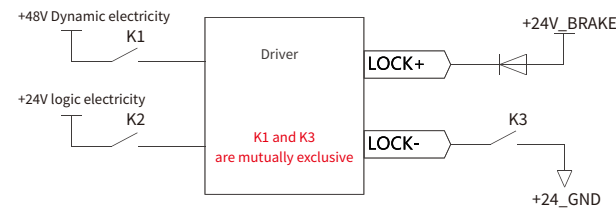


PIN	signal	PIN	signal
1	24V	10	GND
2	LOCK+	11	LOCK-
3	CANH	12	CANL
4	CANH	13	CANL
5	485A	14	485B
6	485A	15	485B
7	OUT1+	16	COMO
8	COMI	17	DI1
9	Empty	18	DI2

iWMC Integrated Servo Wheel Control Wiring Diagram

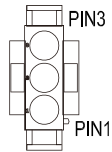


Wiring Diagram of Recommended Circuit for Forced Unlocking Brake



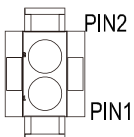
Note: The forced unlocking function needs to be used after the power supply of the servo wheel is cut off.

Power port



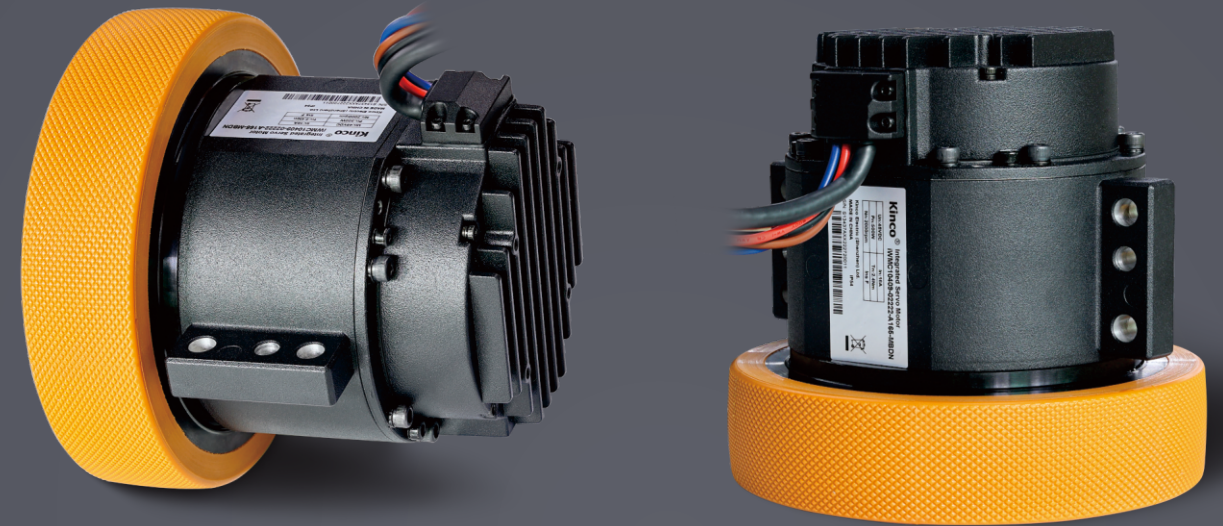
Pin number	Pin name	Pin function
3	DC-	The input end of the power supply of the driver must be connected
1	DC+	Input voltage: 24~60VDC

Brake resistance port



Pin number	Pin name	Pin function
1	RB+	External braking resistor input terminal
2	RB-	

iWMC Integrated Servo Wheel



- ☑ Design of dual power supply for driver
- ☑ Support external forced unlocking
- ☑ Standard Canopen communication protocol
- ☑ The reducer has low back seam and high precision

Superiority

- Highly integrated**: The four main components of the driver, motor, gearhead, and wheel are highly integrated, resulting in a compact structure that facilitates downsizing;
- High mounting accuracy**: Supported mounting, simple and convenient mounting method, high mounting accuracy, and high control accuracy;
- High reliability**: The integrated module, with only external power supply and communication cables, is resistant to nickel-contacts and improves the stability and reliability of the entire system;
- Compatible design & seamless switching**: the communication and usage modes of the servo wheel products are no different from those of the standard Kinco products, allowing seamless switching;
- Good maintainability**: A single supplier for the integrated product facilitates the maintenance of the product at a later stage and reduces supply chain and after-sale costs.

Application Scenario

Power Servo Wheel Module for Mobile Machines with Loads up to 600 kg

iWMC Integrated Servo Wheel

■ Naming convention

iWMC - 104 09 - 022 22 - A 165 - M B D T - XX

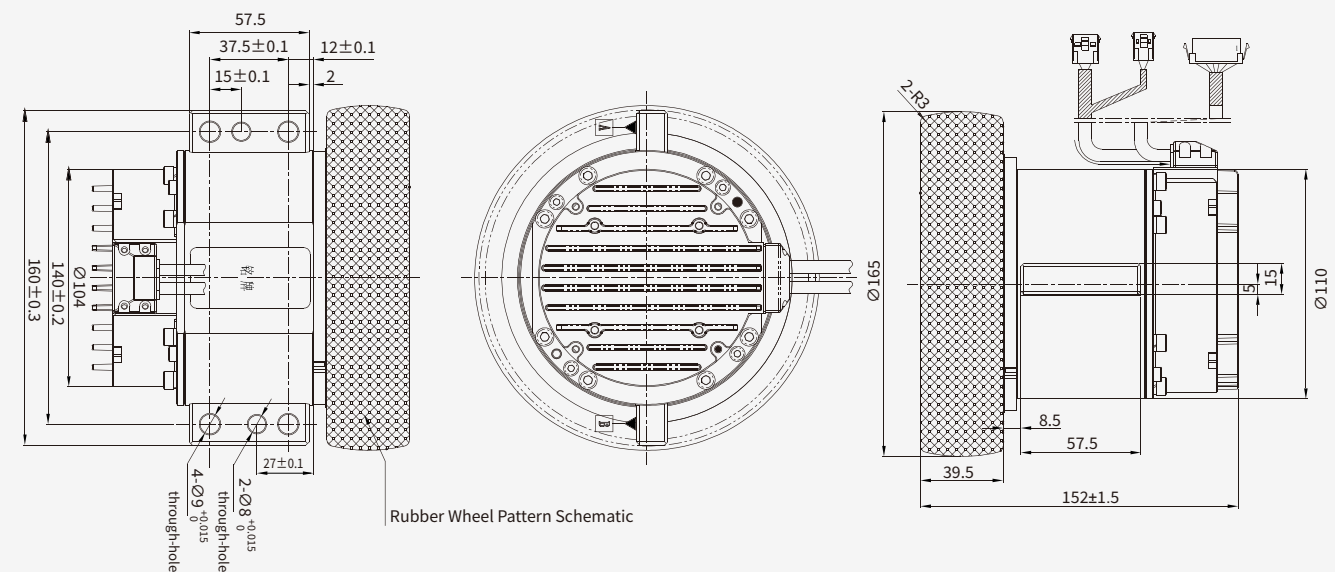
Series name		Special Customization	
iWM	WM: Three-in-one servo wheel	T	XX from 01
	iWM: 4-in-1 servo wheel containing drive		Connector type/wire length, etc.
	C: C series		X: Connector for direct connection to AGV controller
	E: E series		N: 5 separate wire connectors
	H: H series		T: Adapter connector, molex+systemtop
S: S series			
Outer diameter of motor stator		Supply voltage	
104	104mm	D	D: DC48V
Reducer speed ratio		Brake	
09	9 speed ratio	B	B: With brake A: Without brake
Torque		Encoder type	
022	22Nm	M	M: Singleturn communication type magnetoelectric encoder
Wheel speed (after reducer output)			W: 2500P/R incremental magnetoelectric encoder
22	22*10rpm		Z: Dual Encoder
Wheel Covering Material/Pattern Type		Wheel outer diameter	
A	Polyurethane/Raised cross-section, diamond pattern	165	165mm
0	No rubber covered wheel	000	0mm

■ Parameter specification

iWMC Integrated Servo Wheel Model Number		iWMC10409-02222-A165-MBDT	iWMC10409-02222-0000-MBDT	iWMC10409-02222-A165-MADT	iWMC10409-02222-0000-MADT
Power	Power Supply	24VDC~60VDC			
	Logic Supply	24VDC			
Rated Linear Speed (m/s)		1.9m/s			
Rated Torque Tn(Nm)		21Nm			
Peak Torque Tn(Nm)		60Nm			
Tire Diameter (mm)		165			
Tire Width (mm)		39.5			
Tire Material		Polyurethane (optional)			
Tire Hardness Rating		85A			
Energy Consumption Braking		External braking resistor is required (depending on the operating conditions, mainly used for rapid starting and stopping)			
Energy Consumption Braking Voltage Absorption Point		2 digital inputs / Common COM1 terminal / High level: 12.5-30VDC / Low level: 0-5VDC / Maximum frequency: 1KHz / Input impedance: 5KΩ.			
Overvoltage alarm point		1 digital output common COM0 terminal / Maximum output current: 100mA			
Undervoltage alarm point		Built-in brake and control circuit			
Input Specifications		1-way forced unlock interface, only for use when there is no power input to the servo wheel.			
Output Specifications		DC63V ± 2V (Default, settable)			
Brake		DC68V ± 2V	None		
Forced Unlock Interface		DC18V ± 2V	None		
RS485 Debug Port		Maximum support for 115.2Kbps baud rate			
CAN BUS		Maximum support for 1Mbps baud rate, CANopen protocol can be used to communicate with the controller			
Drive Current	Max. continuous output current (rms)	16Arms			
	Peak Current (PEAK)	64Ap			
Motor	Rated RPM nN(rpm)	2000			
	Rated Torque Tn(Nm)	2.4			
	Brake Holding Torque T(Nm)	4	None		
Noise		<65dB			
Cooling Methods		Natural cooling & Body-assisted cooling			
Operating Environment	Operating Temperature	0~40°C			
	Storage Temperature	-20°C~60°C			
	Humidity (non-condensing)	90%RH below			
	Protection Level	IP54			
	Altitude	The rated working altitude is up to 1000m above sea level. For working altitudes above 1000m, a reduction of 1.5% is required for every 100 meters of rise in altitude, with a maximum working altitude of 4000 meters above sea level.			
Atmospheric Pressure		86kpa~106kpa			

iWMC Integrated Servo Wheel

■ Dimension drawing



■ External wiring diagram

